

NAG Library Routine Document

G07EAF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of ***bold italicised*** terms and other implementation-dependent details.

1 Purpose

G07EAF computes a rank based (nonparametric) estimate and confidence interval for the location parameter of a single population.

2 Specification

```

SUBROUTINE G07EAF(METHOD, N, X, CLEVEL, THETA, THETAL, THETAU, ESTCL,
1                WLOWER, WUPPER, WRK, IWRK, IFAIL)

INTEGER          N, IWRK(3*N), IFAIL
double precision X(N), CLEVEL, THETA, THETAL, THETAU, ESTCL, WLOWER,
1                WUPPER, WRK(4*N)
CHARACTER*1      METHOD

```

3 Description

Consider a vector of independent observations, $x = (x_1, x_2, \dots, x_n)^T$ with unknown common symmetric density $f(x_i - \theta)$. G07EAF computes the Hodges–Lehmann location estimator (see Lehmann (1975)) of the centre of symmetry θ , together with an associated confidence interval. The Hodges–Lehmann estimate is defined as

$$\hat{\theta} = \text{median} \left\{ \frac{x_i + x_j}{2}, 1 \leq i \leq j \leq n \right\}.$$

Let $m = (n(n+1))/2$ and let a_k , for $k = 1, 2, \dots, m$ denote the m ordered averages $(x_i + x_j)/2$ for $1 \leq i \leq j \leq n$. Then

if m is odd, $\hat{\theta} = a_k$ where $k = (m+1)/2$;

if m is even, $\hat{\theta} = (a_k + a_{k+1})/2$ where $k = m/2$.

This estimator arises from inverting the one-sample Wilcoxon signed-rank test statistic, $W(x - \theta_0)$, for testing the hypothesis that $\theta = \theta_0$. Effectively $W(x - \theta_0)$ is a monotonically decreasing step function of θ_0 with

$$\text{mean}(W) = \mu = \frac{n(n+1)}{4},$$

$$\text{var}(W) = \sigma^2 = \frac{n(n+1)(2n+1)}{24}.$$

The estimate $\hat{\theta}$ is the solution to the equation $W(x - \hat{\theta}) = \mu$; two methods are available for solving this equation. These methods avoid the computation of all the ordered averages a_k ; this is because for large n both the storage requirements and the computation time would be excessive.

The first is an exact method based on a set partitioning procedure on the set of all ordered averages $(x_i + x_j)/2$ for $i \leq j$. This is based on the algorithm proposed by Monahan (1984).

The second is an iterative algorithm, based on the Illinois method which is a modification of the *regula falsi* method, see McKean and Ryan (1977). This algorithm has proved suitable for the function $W(x - \theta_0)$ which is asymptotically linear as a function of θ_0 .

The confidence interval limits are also based on the inversion of the Wilcoxon test statistic.

Given a desired percentage for the confidence interval, $1 - \alpha$, expressed as a proportion between 0 and 1, initial estimates for the lower and upper confidence limits of the Wilcoxon statistic are found from

$$W_l = \mu - 0.5 + (\sigma\Phi^{-1}(\alpha/2))$$

and

$$W_u = \mu + 0.5 + (\sigma\Phi^{-1}(1 - \alpha/2)),$$

where Φ^{-1} is the inverse cumulative Normal distribution function.

W_l and W_u are rounded to the nearest integer values. These estimates are then refined using an exact method if $n \leq 80$, and a Normal approximation otherwise, to find W_l and W_u satisfying

$$\begin{aligned} P(W \leq W_l) &\leq \alpha/2 \\ P(W \leq W_l + 1) &> \alpha/2 \end{aligned}$$

and

$$\begin{aligned} P(W \geq W_u) &\leq \alpha/2 \\ P(W \geq W_u - 1) &> \alpha/2. \end{aligned}$$

Let $W_u = m - k$; then $\theta_l = a_{k+1}$. This is the largest value θ_l such that $W(x - \theta_l) = W_u$.

Let $W_l = k$; then $\theta_u = a_{m-k}$. This is the smallest value θ_u such that $W(x - \theta_u) = W_l$.

As in the case of $\hat{\theta}$, these equations may be solved using either the exact or the iterative methods to find the values θ_l and θ_u .

Then (θ_l, θ_u) is the confidence interval for θ . The confidence interval is thus defined by those values of θ_0 such that the null hypothesis, $\theta = \theta_0$, is not rejected by the Wilcoxon signed-rank test at the $(100 \times \alpha)\%$ level.

4 References

Lehmann E L (1975) *Nonparametrics: Statistical Methods Based on Ranks* Holden-Day

Marazzi A (1987) Subroutines for robust estimation of location and scale in ROBETH *Cah. Rech. Doc. IUMSP, No. 3 ROB 1* Institut Universitaire de Médecine Sociale et Préventive, Lausanne

McKean J W and Ryan T A (1977) Algorithm 516: An algorithm for obtaining confidence intervals and point estimates based on ranks in the two-sample location problem *ACM Trans. Math. Software* **10** 183–185

Monahan J F (1984) Algorithm 616: Fast computation of the Hodges–Lehman location estimator *ACM Trans. Math. Software* **10** 265–270

5 Parameters

- 1: METHOD – CHARACTER*1 Input
On entry: specifies the method to be used.
 If METHOD = 'E', the exact algorithm is used.
 If METHOD = 'A', the iterative algorithm is used.
Constraint: METHOD = 'E' or 'A'.
- 2: N – INTEGER Input
On entry: n , the sample size.
Constraint: $N \geq 2$.
- 3: X(N) – **double precision** array Input
On entry: the sample observations, x_i for $i = 1, 2, \dots, n$.

- 4: CLEVEL – *double precision* *Input*
On entry: the confidence interval desired.
 For example, for a 95% confidence interval set CLEVEL = 0.95.
Constraint: $0.0 < \text{CLEVEL} < 1.0$.
- 5: THETA – *double precision* *Output*
On exit: the estimate of the location, $\hat{\theta}$.
- 6: THETAL – *double precision* *Output*
On exit: the estimate of the lower limit of the confidence interval, θ_l .
- 7: THETAU – *double precision* *Output*
On exit: the estimate of the upper limit of the confidence interval, θ_u .
- 8: ESTCL – *double precision* *Output*
On exit: an estimate of the actual percentage confidence of the interval found, as a proportion between (0.0, 1.0).
- 9: WLOWER – *double precision* *Output*
On exit: the upper value of the Wilcoxon test statistic, W_u , corresponding to the lower limit of the confidence interval.
- 10: WUPPER – *double precision* *Output*
On exit: the lower value of the Wilcoxon test statistic, W_l , corresponding to the upper limit of the confidence interval.
- 11: WRK(4 × N) – *double precision* array *Workspace*
 12: IWRK(3 × N) – INTEGER array *Workspace*
- 13: IFAIL – INTEGER *Input/Output*
On entry: IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this parameter you should refer to Section 3.3 in the Essential Introduction for details.
On exit: IFAIL = 0 unless the routine detects an error (see Section 6).
 For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, if you are not familiar with this parameter, the recommended value is 0. **When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.**

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

On entry, METHOD $\neq$ 'E' or 'A',
 or $N < 2$,
 or $\text{CLEVEL} \leq 0.0$,
 or $\text{CLEVEL} \geq 1.0$.

IFAIL = 2

There is not enough information to compute a confidence interval since the whole sample consists of identical values.

IFAIL = 3

For at least one of the estimates $\hat{\theta}$, θ_l and θ_u , the underlying iterative algorithm (when METHOD = 'A') failed to converge. This is an unlikely exit but the estimate should still be a reasonable approximation.

7 Accuracy

G07EAF should produce results accurate to five significant figures in the width of the confidence interval; that is the error for any one of the three estimates should be less than $0.00001 \times (\text{THETAU} - \text{THETAL})$.

8 Further Comments

The time taken increases with the sample size n .

9 Example

The following program calculates a 95% confidence interval for θ , a measure of symmetry of the sample of 50 observations.

9.1 Program Text

```
*      G07EAF Example Program Text
*      Mark 16 Release. NAG Copyright 1992.
*      .. Parameters ..
      INTEGER          NIN, NOUT
      PARAMETER        (NIN=5,NOUT=6)
      INTEGER          NMAX
      PARAMETER        (NMAX=100)
*      .. Local Scalars ..
      DOUBLE PRECISION CLEVEL, ESTCL, THETA, THETAL, THETAU, WLOWER,
+      WUPPER
      INTEGER          I, IFAIL, N
*      .. Local Arrays ..
      DOUBLE PRECISION WRK(4*NMAX), X(NMAX)
      INTEGER          IWRK(3*NMAX)
*      .. External Subroutines ..
      EXTERNAL         G07EAF
*      .. Executable Statements ..
      WRITE (NOUT,*) 'G07EAF Example Program Results'
*      Skip heading in data file
      READ (NIN,*)
      READ (NIN,*) N
      IF (N.LE.1 .OR. N.GT.NMAX) THEN
         WRITE (NOUT,99999) N
      ELSE
         READ (NIN,*) (X(I),I=1,N)
         READ (NIN,*) CLEVEL
         IFAIL = 0
*
         CALL G07EAF('Exact',N,X,CLEVEL,THETA,THETAL,THETAU,ESTCL,
+      WLOWER,WUPPER,WRK,IWRK,IFAIL)
*
         WRITE (NOUT,*)
         WRITE (NOUT,*) ' Location estimator      Confidence Interval '
         WRITE (NOUT,*)
         WRITE (NOUT,99998) THETA, '( ', THETAL, ' , ', THETAU, ' )'
         WRITE (NOUT,*)
         WRITE (NOUT,*) ' Corresponding Wilcoxon statistics'
         WRITE (NOUT,*)
```

```

        WRITE (NOUT,99997) ' Lower : ', WLOWER
        WRITE (NOUT,99997) ' Upper : ', WUPPER
    END IF
*
99999 FORMAT (1X,'N is less than 2 or greater than NMAX : N = ',I8)
99998 FORMAT (3X,F10.4,12X,A,F6.4,A,F6.4,A)
99997 FORMAT (A,F8.2)
END

```

9.2 Program Data

G07EAF Example Program Data

```

40
-0.23  0.35 -0.77  0.35  0.27 -0.72  0.08 -0.40 -0.76  0.45
 0.73  0.74  0.83 -0.87  0.21  0.29 -0.91 -0.04  0.82 -0.38
-0.31  0.24 -0.47 -0.68 -0.77 -0.86 -0.59  0.73  0.39 -0.44
 0.63 -0.22 -0.07 -0.43 -0.21 -0.31  0.64 -1.00 -0.86 -0.73
0.95

```

9.3 Program Results

G07EAF Example Program Results

Location estimator	Confidence Interval
-0.1300	(-.3300 , 0.0350)

Corresponding Wilcoxon statistics

```

Lower :    556.00
Upper :    264.00

```
