

NAG Library Routine Document

F08QYF (ZTRSNA)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of ***bold italicised*** terms and other implementation-dependent details.

1 Purpose

F08QYF (ZTRSNA) estimates condition numbers for specified eigenvalues and/or right eigenvectors of a complex upper triangular matrix.

2 Specification

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SUBROUTINE F08QYF(JOB, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR, LDVR, S,
1              SEP, MM, M, WORK, LDWORK, RWORK, INFO)
INTEGER          N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO
double precision S(*), SEP(*), RWORK(*)
complex*16      T(LDT,*), VL(LDVL,*), VR(LDVR,*), WORK(LDWORK,*)
LOGICAL          SELECT(*)
CHARACTER*1      JOB, HOWMNY

```

The routine may be called by its LAPACK name ***ztrsna***.

3 Description

F08QYF (ZTRSNA) estimates condition numbers for specified eigenvalues and/or right eigenvectors of a complex upper triangular matrix T . These are the same as the condition numbers of the eigenvalues and right eigenvectors of an original matrix $A = ZTZ^H$ (with unitary Z), from which T may have been derived.

F08QYF (ZTRSNA) computes the reciprocal of the condition number of an eigenvalue λ_i as

$$s_i = \frac{|v^H u|}{\|u\|_E \|v\|_E},$$

where u and v are the right and left eigenvectors of T , respectively, corresponding to λ_i . This reciprocal condition number always lies between zero (i.e., ill-conditioned) and one (i.e., well-conditioned).

An approximate error estimate for a computed eigenvalue λ_i is then given by

$$\frac{\epsilon \|T\|}{s_i},$$

where ϵ is the ***machine precision***.

To estimate the reciprocal of the condition number of the right eigenvector corresponding to λ_i , the routine first calls F08QTF (ZTREXC) to reorder the eigenvalues so that λ_i is in the leading position:

$$T = Q \begin{pmatrix} \lambda_i & c^H \\ 0 & T_{22} \end{pmatrix} Q^H.$$

The reciprocal condition number of the eigenvector is then estimated as sep_i , the smallest singular value of the matrix $(T_{22} - \lambda_i I)$. This number ranges from zero (i.e., ill-conditioned) to very large (i.e., well-conditioned).

An approximate error estimate for a computed right eigenvector u corresponding to λ_i is then given by

$$\frac{\epsilon \|T\|}{sep_i}.$$

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

- 1: JOB – CHARACTER*1 *Input*
On entry: indicates whether condition numbers are required for eigenvalues and/or eigenvectors.
 JOB = 'E'
 Condition numbers for eigenvalues only are computed.
 JOB = 'V'
 Condition numbers for eigenvectors only are computed.
 JOB = 'B'
 Condition numbers for both eigenvalues and eigenvectors are computed.
Constraint: JOB = 'E', 'V' or 'B'.
- 2: HOWMNY – CHARACTER*1 *Input*
On entry: indicates how many condition numbers are to be computed.
 HOWMNY = 'A'
 Condition numbers for all eigenpairs are computed.
 HOWMNY = 'S'
 Condition numbers for selected eigenpairs (as specified by SELECT) are computed.
Constraint: HOWMNY = 'A' or 'S'.
- 3: SELECT(*) – LOGICAL array *Input*
Note: the dimension of the array SELECT must be at least $\max(1, N)$ if HOWMNY = 'S', and at least 1 otherwise.
On entry: specifies the eigenpairs for which condition numbers are to be computed if HOWMNY = 'S'. To select condition numbers for the eigenpair corresponding to the eigenvalue λ_j , SELECT(*j*) must be set to .TRUE..
 If HOWMNY = 'A', SELECT is not referenced.
- 4: N – INTEGER *Input*
On entry: *n*, the order of the matrix *T*.
Constraint: $N \geq 0$.
- 5: T(LDT,*) – **complex*16** array *Input*
Note: the second dimension of the array T must be at least $\max(1, N)$.
On entry: the *n* by *n* upper triangular matrix *T*, as returned by F08PSF (ZHSEQR).
- 6: LDT – INTEGER *Input*
On entry: the first dimension of the array T as declared in the (sub)program from which F08QYF (ZTRSNA) is called.
Constraint: $LDT \geq \max(1, N)$.

- 7: VL(LDVL,*) – **complex*16** array *Input*
Note: the second dimension of the array VL must be at least $\max(1, MM)$ if JOB = 'E' or 'B' and at least 1 if JOB = 'V'.
On entry: if JOB = 'E' or 'B', VL must contain the left eigenvectors of T (or of any matrix QTQ^H with Q unitary) corresponding to the eigenpairs specified by HOWMNY and SELECT. The eigenvectors **must** be stored in consecutive columns of VL, as returned by F08PXF (ZHSEIN) or F08QXF (ZTREVC).
 If JOB = 'V', VL is not referenced.
- 8: LDVL – INTEGER *Input*
On entry: the first dimension of the array VL as declared in the (sub)program from which F08QYF (ZTRSNA) is called.
Constraints:
 if JOB = 'E' or 'B', $LDVL \geq \max(1, N)$;
 if JOB = 'V', $LDVL \geq 1$.
- 9: VR(LDVR,*) – **complex*16** array *Input*
Note: the second dimension of the array VR must be at least $\max(1, MM)$ if JOB = 'E' or 'B' and at least 1 if JOB = 'V'.
On entry: if JOB = 'E' or 'B', VR must contain the right eigenvectors of T (or of any matrix QTQ^H with Q unitary) corresponding to the eigenpairs specified by HOWMNY and SELECT. The eigenvectors **must** be stored in consecutive columns of VR, as returned by F08PXF (ZHSEIN) or F08QXF (ZTREVC).
 If JOB = 'V', VR is not referenced.
- 10: LDVR – INTEGER *Input*
On entry: the first dimension of the array VR as declared in the (sub)program from which F08QYF (ZTRSNA) is called.
Constraints:
 if JOB = 'E' or 'B', $LDVR \geq \max(1, N)$;
 if JOB = 'V', $LDVR \geq 1$.
- 11: S(*) – **double precision** array *Output*
Note: the dimension of the array S must be at least $\max(1, MM)$ if JOB = 'E' or 'B' and at least 1 if JOB = 'V'.
On exit: the reciprocal condition numbers of the selected eigenvalues if JOB = 'E' or 'B', stored in consecutive elements of the array. Thus $S(j)$, $SEP(j)$ and the j th columns of VL and VR all correspond to the same eigenpair (but not in general the j th eigenpair unless all eigenpairs have been selected).
 S is not referenced if JOB = 'V'.
- 12: SEP(*) – **double precision** array *Output*
Note: the dimension of the array SEP must be at least $\max(1, MM)$ if JOB = 'V' or 'B' and at least 1 if JOB = 'E'.
On exit: the estimated reciprocal condition numbers of the selected right eigenvectors if JOB = 'V' or 'B', stored in consecutive elements of the array.
 If JOB = 'E', SEP is not referenced i.

- 13: MM – INTEGER *Input*
On entry: the number of elements in the arrays S and SEP, and the number of columns in the arrays VL and VR (if used). The precise number required, m , is n if HOWMNY = 'A'; if HOWMNY = 'S', m is the number of selected eigenpairs (see SELECT), in which case $0 \leq m \leq n$.
Constraint: $MM \geq m$.
- 14: M – INTEGER *Output*
On exit: m , the number of selected eigenpairs. If HOWMNY = 'A', M is set to n .
- 15: WORK(LDWORK,*) – **complex*16** array *Workspace*
Note: the second dimension of the array WORK must be at least $\max(1, N + 1)$ if JOB = 'V' or 'B' and at least 1 if JOB = 'E'.
 If JOB = 'E', WORK is not referenced.
- 16: LDWORK – INTEGER *Input*
On entry: the first dimension of the array WORK as declared in the (sub)program from which F08QYF (ZTRSNA) is called.
Constraints:
 if JOB = 'V' or 'B', $LDWORK \geq \max(1, N)$;
 if JOB = 'E', $LDWORK \geq 1$.
- 17: RWORK(*) – **double precision** array *Workspace*
Note: the dimension of the array RWORK must be at least $\max(1, N)$.
- 18: INFO – INTEGER *Output*
On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

INFO < 0

If INFO = $-i$, argument i had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The computed values sep_i may over estimate the true value, but seldom by a factor of more than 3.

8 Further Comments

The real analogue of this routine is F08QLF (DTRSNA).

9 Example

This example computes approximate error estimates for all the eigenvalues and right eigenvectors of the matrix T , where

$$T = \begin{pmatrix} -6.0004 - 6.9999i & 0.3637 - 0.3656i & -0.1880 + 0.4787i & 0.8785 - 0.2539i \\ 0.0000 + 0.0000i & -5.0000 + 2.0060i & -0.0307 - 0.7217i & -0.2290 + 0.1313i \\ 0.0000 + 0.0000i & 0.0000 + 0.0000i & 7.9982 - 0.9964i & 0.9357 + 0.5359i \\ 0.0000 + 0.0000i & 0.0000 + 0.0000i & 0.0000 + 0.0000i & 3.0023 - 3.9998i \end{pmatrix}.$$

9.1 Program Text

```

*      F08QYF Example Program Text
*      Mark 21 Release. NAG Copyright 2004.
*      .. Parameters ..
      INTEGER          NIN, NOUT
      PARAMETER        (NIN=5,NOUT=6)
      INTEGER          NMAX
      PARAMETER        (NMAX=8)
      INTEGER          LDT, LDWORK, LDVL, LDVR
      PARAMETER        (LDT=NMAX,LDWORK=NMAX,LDVL=NMAX,LDVR=NMAX)
*      .. Local Scalars ..
      DOUBLE PRECISION EPS, TNORM
      INTEGER          I, INFO, J, M, N
*      .. Local Arrays ..
      COMPLEX *16      T(LDT,NMAX), VL(LDVL,NMAX), VR(LDVR,NMAX),
+                     WORK(LDWORK,NMAX+1)
      DOUBLE PRECISION RWORK(NMAX), S(NMAX), SEP(NMAX)
      LOGICAL          SELECT(1)
*      .. External Functions ..
      DOUBLE PRECISION F06UAF, X02AJF
      EXTERNAL          F06UAF, X02AJF
*      .. External Subroutines ..
      EXTERNAL          ZTREVC, ZTRSNA
*      .. Executable Statements ..
      WRITE (NOUT,*) 'F08QYF Example Program Results'
      WRITE (NOUT,*)
*      Skip heading in data file
      READ (NIN,*)
      READ (NIN,*) N
      IF (N.LE.NMAX) THEN
*
*          Read T from data file
*
*          READ (NIN,*) ((T(I,J),J=1,N),I=1,N)
*
*          Calculate the left and right eigenvectors of T
*
*          CALL ZTREVC('Both','All',SELECT,N,T,LDT,VL,LDVL,VR,LDVR,N,M,
+                     WORK,RWORK,INFO)
*
*          Estimate condition numbers for all the eigenvalues and right
*          eigenvectors of T
*
*          CALL ZTRSNA('Both','All',SELECT,N,T,LDT,VL,LDVL,VR,LDVR,S,SEP,
+                     N,M,WORK,LDWORK,RWORK,INFO)
*
*          Print condition numbers of eigenvalues and right eigenvectors
*
*          WRITE (NOUT,*) 'S'
*          WRITE (NOUT,99999) (S(I),I=1,M)
*          WRITE (NOUT,*)
*          WRITE (NOUT,*) 'SEP'
*          WRITE (NOUT,99999) (SEP(I),I=1,M)
*
*          Calculate approximate error estimates (using the 1-norm)
*
*          EPS = X02AJF()
*          TNORM = F06UAF('1-norm',N,N,T,LDT,RWORK)
*          WRITE (NOUT,*)
*          WRITE (NOUT,*) 'Approximate error estimates for eigenvalues ',
+          'of T (machine-dependent)'
*          WRITE (NOUT,99999) (EPS*TNORM/S(I),I=1,M)
*          WRITE (NOUT,*)
*          WRITE (NOUT,*) 'Approximate error estimates for right ',
+          'eigenvectors of T (machine-dependent)'
*          WRITE (NOUT,99999) (EPS*TNORM/SEP(I),I=1,M)
      ELSE

```

```

      WRITE (NOUT,*) 'NMAX too small'
    END IF
*
99999 FORMAT ((3X,1P,7E11.1))
END

```

9.2 Program Data

F08QYF Example Program Data

```

4                                     :Value of N
(-6.0004,-6.9999) ( 0.3637,-0.3656) (-0.1880, 0.4787) ( 0.8785,-0.2539)
( 0.0000, 0.0000) (-5.0000, 2.0060) (-0.0307,-0.7217) (-0.2290, 0.1313)
( 0.0000, 0.0000) ( 0.0000, 0.0000) ( 7.9982,-0.9964) ( 0.9357, 0.5359)
( 0.0000, 0.0000) ( 0.0000, 0.0000) ( 0.0000, 0.0000) ( 3.0023,-3.9998)
                                     :End of matrix T

```

9.3 Program Results

F08QYF Example Program Results

```

S
    9.9E-01    1.0E+00    9.8E-01    9.8E-01

```

```

SEP
    8.4E+00    8.0E+00    5.8E+00    5.8E+00

```

```

Approximate error estimates for eigenvalues of T (machine-dependent)
    1.0E-15    1.0E-15    1.1E-15    1.1E-15

```

```

Approximate error estimates for right eigenvectors of T (machine-dependent)
    1.2E-16    1.3E-16    1.8E-16    1.8E-16

```
