

NAG Library Routine Document

F07PPF (ZHPSVX)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of ***bold italicised*** terms and other implementation-dependent details.

1 Purpose

F07PPF (ZHPSVX) uses the diagonal pivoting factorization

$$A = UDU^H \quad \text{or} \quad A = LDL^H$$

to compute the solution to a complex system of linear equations

$$AX = B,$$

where A is an n by n Hermitian matrix stored in packed format and X and B are n by r matrices. Error bounds on the solution and a condition estimate are also provided.

2 Specification

```

SUBROUTINE F07PPF(FACT, UPLO, N, NRHS, AP, AFP, IPIV, B, LDB, X, LDX,
1              RCOND, FERR, BERR, WORK, RWORK, INFO)
    INTEGER          N, NRHS, IPIV(*), LDB, LDX, INFO
    double precision RCOND, FERR(NRHS), BERR(NRHS), RWORK(N)
    complex*16       AP(*), AFP(*), B(LDB,*), X(LDX,*), WORK(2*N)
    CHARACTER*1      FACT, UPLO

```

The routine may be called by its LAPACK name ***zhpsvx***.

3 Description

F07PPF (ZHPSVX) performs the following steps:

1. If FACT = 'N', the diagonal pivoting method is used to factor A as $A = UDU^H$ if UPLO = 'U' or $A = LDL^H$ if UPLO = 'L', where U (or L) is a product of permutation and unit upper (lower) triangular matrices and D is Hermitian and block diagonal with 1 by 1 and 2 by 2 diagonal blocks.
2. If some $d_{ii} = 0$, so that D is exactly singular, then the routine returns with INFO = i . Otherwise, the factored form of A is used to estimate the condition number of the matrix A . If the reciprocal of the condition number is less than ***machine precision***, INFO = $N + 1$ is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.
3. The system of equations is solved for X using the factored form of A .
4. Iterative refinement is applied to improve the computed solution matrix and to calculate error bounds and backward error estimates for it.

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

Higham N J (2002) *Accuracy and Stability of Numerical Algorithms* (2nd Edition) SIAM, Philadelphia

5 Parameters

- 1: FACT – CHARACTER*1 *Input*
On entry: specifies whether or not the factorized form of the matrix A has been supplied.
 FACT = 'F'
 AFP and IPIV contain the factorized form of the matrix A . AFP and IPIV will not be modified.
 FACT = 'N'
 The matrix A will be copied to AFP and factorized.
Constraint: FACT = 'F' or 'N'.
- 2: UPLO – CHARACTER*1 *Input*
On entry: if UPLO = 'U', the upper triangle of A is stored.
 If UPLO = 'L', the lower triangle of A is stored.
Constraint: UPLO = 'U' or 'L'.
- 3: N – INTEGER *Input*
On entry: n , the number of linear equations, i.e., the order of the matrix A .
Constraint: $N \geq 0$.
- 4: NRHS – INTEGER *Input*
On entry: r , the number of right-hand sides, i.e., the number of columns of the matrix B .
Constraint: NRHS ≥ 0 .
- 5: AP(*) – **complex*16** array *Input*
Note: the dimension of the array AP must be at least $\max(1, N \times (N + 1)/2)$.
On entry: the n by n Hermitian matrix A , packed by columns.
 More precisely,
 if UPLO = 'U', the upper triangle of A must be stored with element A_{ij} in
 AP($i + j(j - 1)/2$) for $i \leq j$;
 if UPLO = 'L', the lower triangle of A must be stored with element A_{ij} in
 AP($i + (2n - j)(j - 1)/2$) for $i \geq j$.
- 6: AFP(*) – **complex*16** array *Input/Output*
Note: the dimension of the array AFP must be at least $\max(1, N \times (N + 1)/2)$.
On entry: if FACT = 'F', AFP contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = UDU^H$ or $A = LDL^H$ as computed by F07PRF (ZHPTRF), stored as a packed triangular matrix in the same storage format as A .
On exit: if FACT = 'N', AFP contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = UDU^H$ or $A = LDL^H$ as computed by F07PRF (ZHPTRF), stored as a packed triangular matrix in the same storage format as A .

- 7: IPIV(*) – INTEGER array Input/Output
Note: the dimension of the array IPIV must be at least $\max(1, N)$.
On entry: if FACT = 'F', IPIV contains details of the interchanges and the block structure of D , as determined by F07PRF (ZHPTRF).
 $IPIV(k) > 0$
 Rows and columns k and $IPIV(k)$ were interchanged and $D(k, k)$ is a 1 by 1 diagonal block.
 $UPLO = 'U'$ and $IPIV(k) = IPIV(k - 1) < 0$
 Rows and columns $k - 1$ and $-IPIV(k)$ were interchanged and $D(k - 1 : k, k - 1 : k)$ is a 2 by 2 diagonal block.
 $UPLO = 'L'$ and $IPIV(k) = IPIV(k + 1) < 0$
 Rows and columns $k + 1$ and $-IPIV(k)$ were interchanged and $D(k : k + 1, k : k + 1)$ is a 2 by 2 diagonal block.
On exit: if FACT = 'N', IPIV contains details of the interchanges and the block structure of D , as determined by F07PRF (ZHPTRF).
- 8: B(LDB,*) – **complex*16** array Input
Note: the second dimension of the array B must be at least $\max(1, NRHS)$.
On entry: the n by r right-hand side matrix B .
- 9: LDB – INTEGER Input
On entry: the first dimension of the array B as declared in the (sub)program from which F07PPF (ZHPSVX) is called.
Constraint: $LDB \geq \max(1, N)$.
- 10: X(LDX,*) – **complex*16** array Output
Note: the second dimension of the array X must be at least $\max(1, NRHS)$.
On exit: if INFO = 0 or $N + 1$, the n by r solution matrix X .
- 11: LDX – INTEGER Input
On entry: the first dimension of the array X as declared in the (sub)program from which F07PPF (ZHPSVX) is called.
Constraint: $LDX \geq \max(1, N)$.
- 12: RCOND – **double precision** Output
On exit: the estimate of the reciprocal condition number of the matrix A . If RCOND = 0, the matrix may be exactly singular. This condition is indicated by INFO > 0 and INFO ≤ N. Otherwise, if RCOND is less than the **machine precision**, the matrix is singular to working precision. This condition is indicated by INFO = N + 1.
- 13: FERR(NRHS) – **double precision** array Output
On exit: if INFO = 0 or N + 1, an estimate of the forward error bound for each computed solution vector, such that $\|\hat{x}_j - x_j\|_\infty / \|x_j\|_\infty \leq FERR(j)$ where $\hat{x}_j$ is the j th column of the computed solution returned in the array X and x_j is the corresponding column of the exact solution X . The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.
- 14: BERR(NRHS) – **double precision** array Output
On exit: if INFO = 0 or N + 1, an estimate of the component-wise relative backward error of each computed solution vector $\hat{x}_j$ (i.e., the smallest relative change in any element of A or B that makes $\hat{x}_j$ an exact solution).

- 15: WORK($2 \times N$) – *complex*16* array Workspace
- 16: RWORK(N) – *double precision* array Workspace
- 17: INFO – INTEGER Output
- On exit:* INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the routine:

INFO < 0

If INFO = $-i$, the i th argument had an illegal value. An explanatory message is output, and execution of the program is terminated.

INFO > 0 and INFO $\leq N$

If INFO $\leq N$, $d(i, i)$ is exactly zero. The factorization has been completed, but the factor D is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned.

INFO = $N + 1$

D is nonsingular, but RCOND is less than *machine precision*, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

7 Accuracy

For each right-hand side vector b , the computed solution $\hat{x}$ is the exact solution of a perturbed system of equations $(A + E)\hat{x} = b$, where

$$\|E\|_1 = O(\epsilon)\|A\|_1,$$

where ϵ is the *machine precision*. See Chapter 11 of Higham (2002) for further details.

If $\hat{x}$ is the true solution, then the computed solution x satisfies a forward error bound of the form

$$\frac{\|x - \hat{x}\|_\infty}{\|\hat{x}\|_\infty} \leq w_c \text{cond}(A, \hat{x}, b)$$

where $\text{cond}(A, \hat{x}, b) = \frac{\|A^{-1}(|A|\|\hat{x}\| + |b|)\|_\infty}{\|\hat{x}\|_\infty} \leq \text{cond}(A) = \|A^{-1}\|_\infty \|A\|_\infty \leq \kappa_\infty(A)$. If $\hat{x}$ is the j th column of X , then w_c is returned in BERR(j) and a bound on $\|x - \hat{x}\|_\infty / \|\hat{x}\|_\infty$ is returned in FERR(j). See Section 4.4 of Anderson *et al.* (1999) for further details.

8 Further Comments

The factorization of A requires approximately $\frac{4}{3}n^3$ floating-point operations.

For each right-hand side, computation of the backward error involves a minimum of $16n^2$ floating-point operations. Each step of iterative refinement involves an additional $24n^2$ operations. At most five steps of iterative refinement are performed, but usually only one or two steps are required. Estimating the forward error involves solving a number of systems of equations of the form $Ax = b$; the number is usually 4 or 5 and never more than 11. Each solution involves approximately $8n^2$ operations.

The real analogue of this routine is F07PBF (DSPSVX).

9 Example

This example solves the equations

$$Ax = b,$$

where A is the Hermitian matrix

$$A = \begin{pmatrix} -1.84 & 0.11 - 0.11i & -1.78 - 1.18i & 3.91 - 1.50i \\ 0.11 + 0.11i & -4.63 & -1.84 + 0.03i & 2.21 + 0.21i \\ -1.78 + 1.18i & -1.84 - 0.03i & -8.87 & 1.58 - 0.90i \\ 3.91 + 1.50i & 2.21 - 0.21i & 1.58 + 0.90i & -1.36 \end{pmatrix}$$

and

$$B = \begin{pmatrix} 2.98 - 10.18i & 28.68 - 39.89i \\ -9.58 + 3.88i & -24.79 - 8.40i \\ -0.77 - 16.05i & 4.23 - 70.02i \\ 7.79 + 5.48i & -35.39 + 18.01i \end{pmatrix}.$$

Error estimates for the solutions, and an estimate of the reciprocal of the condition number of the matrix A are also output.

9.1 Program Text

```
*      F07PPF Example Program Text
*      Mark 21 Release. NAG Copyright 2004.
*      .. Parameters ..
      INTEGER          NIN, NOUT
      PARAMETER        (NIN=5,NOUT=6)
      INTEGER          NMAX
      PARAMETER        (NMAX=8)
      INTEGER          LDB, LDX, NRHSMX
      PARAMETER        (LDB=NMAX,LDX=NMAX,NRHSMX=NMAX)
      CHARACTER        UPLO
      PARAMETER        (UPLO='U')
*      .. Local Scalars ..
      DOUBLE PRECISION RCOND
      INTEGER          I, IFAIL, INFO, J, N, NRHS
*      .. Local Arrays ..
      COMPLEX *16      AFP((NMAX*(NMAX+1))/2), AP((NMAX*(NMAX+1))/2),
+      B(LDB,NRHSMX), WORK(2*NMAX), X(LDX,NRHSMX)
      DOUBLE PRECISION BERR(NRHSMX), FERR(NRHSMX), RWORK(NMAX)
      INTEGER          IPIV(NMAX)
      CHARACTER        CLABS(1), RLABS(1)
*      .. External Subroutines ..
      EXTERNAL         X04DBF, ZHPSVX
*      .. Executable Statements ..
      WRITE (NOUT,*) 'F07PPF Example Program Results'
      WRITE (NOUT,*)
*      Skip heading in data file
      READ (NIN,*)
      READ (NIN,*) N, NRHS
      IF (N.LE.NMAX .AND. NRHS.LE.NRHSMX) THEN
*
*          Read the upper or lower triangular part of the matrix A from
*          data file
*
*          IF (UPLO.EQ.'U') THEN
*              READ (NIN,*) ((AP(I+(J*(J-1))/2),J=I,N),I=1,N)
*          ELSE IF (UPLO.EQ.'L') THEN
*              READ (NIN,*) ((AP(I+((2*N-J)*(J-1))/2),J=1,I),I=1,N)
*          END IF
*
*          Read B from data file
*
*          READ (NIN,*) ((B(I,J),J=1,NRHS),I=1,N)
*
*          Solve the equations AX = B for X
```

```

*
      CALL ZHPSVX('Not factored',UPLO,N,NRHS,AP,AFP,IPIV,B,LDB,X,LDX,
+              RCOND,FERR,BERR,WORK,RWORK,INFO)
*
      IF ((INFO.EQ.0) .OR. (INFO.EQ.N+1)) THEN
*
*         Print solution, error bounds and condition number
*
          IFAIL = 0
          CALL X04DBF('General',' ',N,NRHS,X,LDX,'Bracketed','F7.4',
+              'Solution(s)','Integer',RLABS,'Integer',CLABS,
+              80,0,IFAIL)
*
          WRITE (NOUT,*)
          WRITE (NOUT,*) 'Backward errors (machine-dependent)'
          WRITE (NOUT,99999) (BERR(J),J=1,NRHS)
          WRITE (NOUT,*)
          WRITE (NOUT,*)
+          'Estimated forward error bounds (machine-dependent)'
          WRITE (NOUT,99999) (FERR(J),J=1,NRHS)
          WRITE (NOUT,*)
          WRITE (NOUT,*) 'Estimate of reciprocal condition number'
          WRITE (NOUT,99999) RCOND
          WRITE (NOUT,*)
*
          IF (INFO.EQ.N+1) THEN
              WRITE (NOUT,*)
              WRITE (NOUT,*)
+              'The matrix A is singular to working precision'
          END IF
          ELSE
              WRITE (NOUT,99998) 'The diagonal block ', INFO,
+              ' of D is zero'
          END IF
          ELSE
              WRITE (NOUT,*) 'NMAX and/or NRHSMX too small'
          END IF
*
99999 FORMAT ((3X,1P,7E11.1))
99998 FORMAT (1X,A,I3,A)
      END

```

9.2 Program Data

F07PPF Example Program Data

```

      4          2                                     :N and NRHS
      ( -1.84,  0.00) (  0.11, -0.11) ( -1.78, -1.18) (  3.91, -1.50)
                        ( -4.63,  0.00) ( -1.84,  0.03) (  2.21,  0.21)
                                      ( -8.87,  0.00) (  1.58, -0.90)
                                                ( -1.36,  0.00) :End matrix A

      (  2.98,-10.18) ( 28.68,-39.89)
      ( -9.58,  3.88) (-24.79, -8.40)
      ( -0.77,-16.05) (  4.23,-70.02)
      (  7.79,  5.48) (-35.39, 18.01)                                     :End matrix B

```

9.3 Program Results

F07PPF Example Program Results

Solution(s)

```

              1          2
1  ( 2.0000, 1.0000) (-8.0000, 6.0000)
2  ( 3.0000,-2.0000) ( 7.0000,-2.0000)
3  (-1.0000, 2.0000) (-1.0000, 5.0000)
4  ( 1.0000,-1.0000) ( 3.0000,-4.0000)

```

Backward errors (machine-dependent)

```

      4.5E-17      1.1E-16

```

Estimated forward error bounds (machine-dependent)

2.5E-15 3.1E-15

Estimate of reciprocal condition number
1.5E-01
