

NAG Library Routine Document

F07MHF (DSYRFS)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of ***bold italicised*** terms and other implementation-dependent details.

1 Purpose

F07MHF (DSYRFS) returns error bounds for the solution of a real symmetric indefinite system of linear equations with multiple right-hand sides, $AX = B$. It improves the solution by iterative refinement, in order to reduce the backward error as much as possible.

2 Specification

```

SUBROUTINE F07MHF(UPLO, N, NRHS, A, LDA, AF, LDAF, IPIV, B, LDB, X, LDX,
1          FERR, BERR, WORK, IWORK, INFO)

INTEGER          N, NRHS, LDA, LDAF, IPIV(*), LDB, LDX, IWORK(N), INFO
double precision A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), FERR(NRHS),
1          BERR(NRHS), WORK(3*N)
CHARACTER*1      UPLO

```

The routine may be called by its LAPACK name ***dsyrfs***.

3 Description

F07MHF (DSYRFS) returns the backward errors and estimated bounds on the forward errors for the solution of a real symmetric indefinite system of linear equations with multiple right-hand sides $AX = B$. The routine handles each right-hand side vector (stored as a column of the matrix B) independently, so we describe the function of F07MHF (DSYRFS) in terms of a single right-hand side b and solution x .

Given a computed solution x , the routine computes the *component-wise backward error* β . This is the size of the smallest relative perturbation in each element of A and b such that x is the exact solution of a perturbed system

$$| \delta a_{ij} | \leq \beta | a_{ij} | \quad \text{and} \quad | \delta b_i | \leq \beta | b_i |.$$

Then the routine estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_i |x_i - \hat{x}_i| / \max_i |x_i|$$

where $\hat{x}$ is the true solution.

For details of the method, see the F07 Chapter Introduction.

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

- 1: UPLO – CHARACTER*1 *Input*
On entry: indicates whether the upper or lower triangular part of A is stored and how A is to be factorized.
UPLO = 'U'
The upper triangular part of A is stored and A is factorized as $PUDU^T P^T$, where U is upper triangular.
UPLO = 'L'
The lower triangular part of A is stored and A is factorized as $PLDL^T P^T$, where L is lower triangular.
Constraint: UPLO = 'U' or 'L'.
- 2: N – INTEGER *Input*
On entry: n , the order of the matrix A .
Constraint: $N \geq 0$.
- 3: NRHS – INTEGER *Input*
On entry: r , the number of right-hand sides.
Constraint: NRHS ≥ 0 .
- 4: A(LDA,*) – **double precision** array *Input*
Note: the second dimension of the array A must be at least $\max(1, N)$.
On entry: the n by n original symmetric matrix A as supplied to F07MDF (DSYTRF).
- 5: LDA – INTEGER *Input*
On entry: the first dimension of the array A as declared in the (sub)program from which F07MHF (DSYRFS) is called.
Constraint: LDA $\geq \max(1, N)$.
- 6: AF(LDAF,*) – **double precision** array *Input*
Note: the second dimension of the array AF must be at least $\max(1, N)$.
On entry: details of the factorization of A , as returned by F07MDF (DSYTRF).
- 7: LDAF – INTEGER *Input*
On entry: the first dimension of the array AF as declared in the (sub)program from which F07MHF (DSYRFS) is called.
Constraint: LDAF $\geq \max(1, N)$.
- 8: IPIV(*) – INTEGER array *Input*
Note: the dimension of the array IPIV must be at least $\max(1, N)$.
On entry: details of the interchanges and the block structure of D , as returned by F07MDF (DSYTRF).

- 9: B(LDB,*) – **double precision** array *Input*
Note: the second dimension of the array B must be at least $\max(1, \text{NRHS})$.
On entry: the n by r right-hand side matrix B .
- 10: LDB – INTEGER *Input*
On entry: the first dimension of the array B as declared in the (sub)program from which F07MHF (DSYRFS) is called.
Constraint: $\text{LDB} \geq \max(1, N)$.
- 11: X(LDX,*) – **double precision** array *Input/Output*
Note: the second dimension of the array X must be at least $\max(1, \text{NRHS})$.
On entry: the n by r solution matrix X , as returned by F07MEF (DSYTRS).
On exit: the improved solution matrix X .
- 12: LDX – INTEGER *Input*
On entry: the first dimension of the array X as declared in the (sub)program from which F07MHF (DSYRFS) is called.
Constraint: $\text{LDX} \geq \max(1, N)$.
- 13: FERR(NRHS) – **double precision** array *Output*
On exit: $\text{FERR}(j)$ contains an estimated error bound for the j th solution vector, that is, the j th column of X , for $j = 1, 2, \dots, r$.
- 14: BERR(NRHS) – **double precision** array *Output*
On exit: $\text{BERR}(j)$ contains the component-wise backward error bound β for the j th solution vector, that is, the j th column of X , for $j = 1, 2, \dots, r$.
- 15: WORK($3 \times N$) – **double precision** array *Workspace*
- 16: IWORK(N) – INTEGER array *Workspace*
- 17: INFO – INTEGER *Output*
On exit: $\text{INFO} = 0$ unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the routine:

$\text{INFO} < 0$

If $\text{INFO} = -i$, the i th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The bounds returned in FERR are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

8 Further Comments

For each right-hand side, computation of the backward error involves a minimum of $4n^2$ floating-point operations. Each step of iterative refinement involves an additional $6n^2$ operations. At most five steps of iterative refinement are performed, but usually only one or two steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form $Ax = b$; the number is usually 4 or 5 and never more than 11. Each solution involves approximately $2n^2$ operations.

The complex analogues of this routine are F07MVF (ZHERFS) for Hermitian matrices and F07NVF (ZSYRFS) for symmetric matrices.

9 Example

This example solves the system of equations $AX = B$ using iterative refinement and to compute the forward and backward error bounds, where

$$A = \begin{pmatrix} 2.07 & 3.87 & 4.20 & -1.15 \\ 3.87 & -0.21 & 1.87 & 0.63 \\ 4.20 & 1.87 & 1.15 & 2.06 \\ -1.15 & 0.63 & 2.06 & -1.81 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} -9.50 & 27.85 \\ -8.38 & 9.90 \\ -6.07 & 19.25 \\ -0.96 & 3.93 \end{pmatrix}.$$

Here A is symmetric indefinite and must first be factorized by F07MDF (DSYTRF).

9.1 Program Text

```
*      F07MHF Example Program Text
*      Mark 15 Release. NAG Copyright 1991.
*      .. Parameters ..
      INTEGER          NIN, NOUT
      PARAMETER        (NIN=5,NOUT=6)
      INTEGER          NMAX, NRHMAX, LDA, LWORK, LDAF, LDB, LDX
      PARAMETER        (NMAX=8,NRHMAX=NMAX,LDA=NMAX,LWORK=64*NMAX,
+                      LDAF=NMAX,LDB=NMAX,LDX=NMAX)
*      .. Local Scalars ..
      INTEGER          I, IFAIL, INFO, J, N, NRHS
      CHARACTER        UPLO
*      .. Local Arrays ..
      DOUBLE PRECISION A(LDA,NMAX), AF(LDAF,NMAX), B(LDB,NRHMAX),
+                      BERR(NRHMAX), FERR(NRHMAX), WORK(LWORK),
+                      X(LDX,NMAX)
      INTEGER          IPIV(NMAX), IWORK(NMAX)
*      .. External Subroutines ..
      EXTERNAL         DSYRFS, DSYTRF, DSYTRS, F06QFF, X04CAF
*      .. Executable Statements ..
      WRITE (NOUT,*) 'F07MHF Example Program Results'
*      Skip heading in data file
      READ (NIN,*)
      READ (NIN,*) N, NRHS
      IF (N.LE.NMAX .AND. NRHS.LE.NRHMAX) THEN
*
*          Read A and B from data file, and copy A to AF and B to X
*
      READ (NIN,*) UPLO
      IF (UPLO.EQ.'U') THEN
          READ (NIN,*) ((A(I,J),J=I,N),I=1,N)
      ELSE IF (UPLO.EQ.'L') THEN
          READ (NIN,*) ((A(I,J),J=1,I),I=1,N)
      END IF
      READ (NIN,*) ((B(I,J),J=1,NRHS),I=1,N)
*
      CALL F06QFF(UPLO,N,N,A,LDA,AF,LDAF)
*
      CALL F06QFF('General',N,NRHS,B,LDB,X,LDX)
*
*      Factorize A in the array AF
```

```

*
      CALL DSYTRF(UPLO,N,AF,LDAF,IPIV,WORK,LWORK,INFO)
*
      WRITE (NOUT,*)
      IF (INFO.EQ.0) THEN
*
*         Compute solution in the array X
*
      CALL DSYTRS(UPLO,N,NRHS,AF,LDAF,IPIV,X,LDX,INFO)
*
*         Improve solution, and compute backward errors and
*         estimated bounds on the forward errors
*
      CALL DSYRFS(UPLO,N,NRHS,A,LDA,AF,LDAF,IPIV,B,LDB,X,LDX,FERR,
+              BERR,WORK,IWORK,INFO)
*
*         Print solution
*
      IFAIL = 0
*
      CALL X04CAF('General',' ',N,NRHS,X,LDX,'Solution(s)',IFAIL)
*
      WRITE (NOUT,*)
      WRITE (NOUT,*) 'Backward errors (machine-dependent)'
      WRITE (NOUT,99999) (BERR(J),J=1,NRHS)
      WRITE (NOUT,*)
+      'Estimated forward error bounds (machine-dependent)'
      WRITE (NOUT,99999) (FERR(J),J=1,NRHS)
      ELSE
      WRITE (NOUT,*) 'The factor D is singular'
      END IF
      END IF
*
99999 FORMAT ((3X,1P,7E11.1))
      END

```

9.2 Program Data

F07MHF Example Program Data

```

4 2          :Values of N and NRHS
'L'          :Value of UPLO
2.07
3.87 -0.21
4.20 1.87 1.15
-1.15 0.63 2.06 -1.81 :End of matrix A
-9.50 27.85
-8.38 9.90
-6.07 19.25
-0.96 3.93          :End of matrix B

```

9.3 Program Results

F07MHF Example Program Results

Solution(s)

	1	2
1	-4.0000	1.0000
2	-1.0000	4.0000
3	2.0000	3.0000
4	5.0000	2.0000

Backward errors (machine-dependent)

9.9E-17 8.3E-17

Estimated forward error bounds (machine-dependent)

2.4E-14 3.2E-14