

# NAG Library Routine Document

## F07HHF (DPBRFS)

**Note:** before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

### 1 Purpose

F07HHF (DPBRFS) returns error bounds for the solution of a real symmetric positive-definite band system of linear equations with multiple right-hand sides,  $AX = B$ . It improves the solution by iterative refinement, in order to reduce the backward error as much as possible.

### 2 Specification

```

SUBROUTINE F07HHF(UPLO, N, KD, NRHS, AB, LDAB, AFB, LDAFB, B, LDB, X,
1          LDX, FERR, BERR, WORK, IWORK, INFO)

INTEGER          N, KD, NRHS, LDAB, LDAFB, LDB, LDX, IWORK(N), INFO
double precision AB(LDAB,*), AFB(LDAFB,*), B(LDB,*), X(LDX,*),
1          FERR(NRHS), BERR(NRHS), WORK(3*N)
CHARACTER*1      UPLO

```

The routine may be called by its LAPACK name *dpbrfs*.

### 3 Description

F07HHF (DPBRFS) returns the backward errors and estimated bounds on the forward errors for the solution of a real symmetric positive-definite band system of linear equations with multiple right-hand sides  $AX = B$ . The routine handles each right-hand side vector (stored as a column of the matrix  $B$ ) independently, so we describe the function of F07HHF (DPBRFS) in terms of a single right-hand side  $b$  and solution  $x$ .

Given a computed solution  $x$ , the routine computes the *component-wise backward error*  $\beta$ . This is the size of the smallest relative perturbation in each element of  $A$  and  $b$  such that  $x$  is the exact solution of a perturbed system

$$| \delta a_{ij} | \leq \beta | a_{ij} | \quad \text{and} \quad (A + \delta A)x = b + \delta b \quad | \delta b_i | \leq \beta | b_i |.$$

Then the routine estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_i |x_i - \hat{x}_i| / \max_i |x_i|$$

where  $\hat{x}$  is the true solution.

For details of the method, see the F07 Chapter Introduction.

## 4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

## 5 Parameters

- 1: UPLO – CHARACTER\*1 *Input*  
*On entry:* indicates whether the upper or lower triangular part of  $A$  is stored and how  $A$  is to be factorized.  
UPLO = 'U'  
The upper triangular part of  $A$  is stored and  $A$  is factorized as  $U^T U$ , where  $U$  is upper triangular.  
UPLO = 'L'  
The lower triangular part of  $A$  is stored and  $A$  is factorized as  $LL^T$ , where  $L$  is lower triangular.  
*Constraint:* UPLO = 'U' or 'L'.
- 2: N – INTEGER *Input*  
*On entry:*  $n$ , the order of the matrix  $A$ .  
*Constraint:*  $N \geq 0$ .
- 3: KD – INTEGER *Input*  
*On entry:*  $k_d$ , the number of superdiagonals or subdiagonals of the matrix  $A$ .  
*Constraint:*  $KD \geq 0$ .
- 4: NRHS – INTEGER *Input*  
*On entry:*  $r$ , the number of right-hand sides.  
*Constraint:*  $NRHS \geq 0$ .
- 5: AB(LDAB,\*) – *double precision* array *Input*  
**Note:** the second dimension of the array AB must be at least  $\max(1, N)$ .  
*On entry:* the  $n$  by  $n$  original symmetric positive-definite band matrix  $A$  as supplied to F07HDF (DPBTRF).
- 6: LDAB – INTEGER *Input*  
*On entry:* the first dimension of the array AB as declared in the (sub)program from which F07HHF (DPBRFS) is called.  
*Constraint:*  $LDAB \geq KD + 1$ .
- 7: AFB(LDAFB,\*) – *double precision* array *Input*  
**Note:** the second dimension of the array AFB must be at least  $\max(1, N)$ .  
*On entry:* the Cholesky factor of  $A$ , as returned by F07HDF (DPBTRF).
- 8: LDAFB – INTEGER *Input*  
*On entry:* the first dimension of the array AFB as declared in the (sub)program from which F07HHF (DPBRFS) is called.  
*Constraint:*  $LDAFB \geq KD + 1$ .

- 9: B(LDB,\*) – **double precision** array *Input*  
**Note:** the second dimension of the array B must be at least  $\max(1, \text{NRHS})$ .  
*On entry:* the  $n$  by  $r$  right-hand side matrix  $B$ .
- 10: LDB – INTEGER *Input*  
*On entry:* the first dimension of the array B as declared in the (sub)program from which F07HHF (DPBRFS) is called.  
*Constraint:*  $\text{LDB} \geq \max(1, N)$ .
- 11: X(LDX,\*) – **double precision** array *Input/Output*  
**Note:** the second dimension of the array X must be at least  $\max(1, \text{NRHS})$ .  
*On entry:* the  $n$  by  $r$  solution matrix  $X$ , as returned by F07HEF (DPBTRS).  
*On exit:* the improved solution matrix  $X$ .
- 12: LDX – INTEGER *Input*  
*On entry:* the first dimension of the array X as declared in the (sub)program from which F07HHF (DPBRFS) is called.  
*Constraint:*  $\text{LDX} \geq \max(1, N)$ .
- 13: FERR(NRHS) – **double precision** array *Output*  
*On exit:*  $\text{FERR}(j)$  contains an estimated error bound for the  $j$ th solution vector, that is, the  $j$ th column of  $X$ , for  $j = 1, 2, \dots, r$ .
- 14: BERR(NRHS) – **double precision** array *Output*  
*On exit:*  $\text{BERR}(j)$  contains the component-wise backward error bound  $\beta$  for the  $j$ th solution vector, that is, the  $j$ th column of  $X$ , for  $j = 1, 2, \dots, r$ .
- 15: WORK( $3 \times N$ ) – **double precision** array *Workspace*
- 16: IWORK(N) – INTEGER array *Workspace*
- 17: INFO – INTEGER *Output*  
*On exit:*  $\text{INFO} = 0$  unless the routine detects an error (see Section 6).

## 6 Error Indicators and Warnings

Errors or warnings detected by the routine:

$\text{INFO} < 0$

If  $\text{INFO} = -i$ , the  $i$ th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

## 7 Accuracy

The bounds returned in FERR are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

## 8 Further Comments

For each right-hand side, computation of the backward error involves a minimum of  $8nk$  floating-point operations. Each step of iterative refinement involves an additional  $12nk$  operations. This assumes

$n \gg k$ . At most five steps of iterative refinement are performed, but usually only one or two steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form  $Ax = b$ ; the number is usually 4 or 5 and never more than 11. Each solution involves approximately  $4nk$  operations.

The complex analogue of this routine is F07HVF (ZPBRFS).

## 9 Example

This example solves the system of equations  $AX = B$  using iterative refinement and to compute the forward and backward error bounds, where

$$A = \begin{pmatrix} 5.49 & 2.68 & 0.00 & 0.00 \\ 2.68 & 5.63 & -2.39 & 0.00 \\ 0.00 & -2.39 & 2.60 & -2.22 \\ 0.00 & 0.00 & -2.22 & 5.17 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 22.09 & 5.10 \\ 9.31 & 30.81 \\ -5.24 & -25.82 \\ 11.83 & 22.90 \end{pmatrix}.$$

Here  $A$  is symmetric and positive-definite, and is treated as a band matrix, which must first be factorized by F07HDF (DPBTRF).

### 9.1 Program Text

```
*      F07HHF Example Program Text
*      Mark 15 Release. NAG Copyright 1991.
*      .. Parameters ..
      INTEGER          NIN, NOUT
      PARAMETER        (NIN=5,NOUT=6)
      DOUBLE PRECISION ZERO
      PARAMETER        (ZERO=0.0D0)
      INTEGER          NMAX, NRHMAX, KDMAX, LDAB, LDAFB, LDB, LDX
      PARAMETER        (NMAX=8,NRHMAX=NMAX,KDMAX=8,LDAB=KDMAX+1,
+                      LDAFB=KDMAX+1,LDB=NMAX,LDX=NMAX)
*      .. Local Scalars ..
      INTEGER          I, IFAIL, INFO, J, KD, N, NRHS
      CHARACTER        UPLO
*      .. Local Arrays ..
      DOUBLE PRECISION AB(LDAB,NMAX), AFB(LDAFB,NMAX), B(LDB,NRHMAX),
+                      BERR(NRHMAX), FERR(NRHMAX), WORK(3*NMAX),
+                      X(LDX,NMAX)
      INTEGER          IWORK(NMAX)
*      .. External Subroutines ..
      EXTERNAL         DPBRFS, DPBTRF, DPBTRS, F06QFF, F06QHF, X04CAF
*      .. Intrinsic Functions ..
      INTRINSIC        MAX, MIN
*      .. Executable Statements ..
      WRITE (NOUT,*) 'F07HHF Example Program Results'
*      Skip heading in data file
      READ (NIN,*)
      READ (NIN,*) N, KD, NRHS
      IF (N.LE.NMAX .AND. KD.LE.KDMAX .AND. NRHS.LE.NRHMAX) THEN
*
*          Set A to zero to avoid referencing uninitialized elements
*
*          CALL F06QHF('General',KD+1,N,ZERO,ZERO,AB,LDAB)
*
*          Read A and B from data file, and copy A to AFB and B to X
*
      READ (NIN,*) UPLO
      IF (UPLO.EQ.'U') THEN
        DO 20 I = 1, N
          READ (NIN,*) (AB(KD+1+I-J,J),J=I,MIN(N,I+KD))
20      CONTINUE
      ELSE IF (UPLO.EQ.'L') THEN
        DO 40 I = 1, N
          READ (NIN,*) (AB(1+I-J,J),J=MAX(1,I-KD),I)
40      CONTINUE
```

```

      END IF
      READ (NIN,*) ((B(I,J),J=1,NRHS),I=1,N)
*
      CALL F06QFF('General',KD+1,N,AB,LDAB,AFB,LDAFB)
*
      CALL F06QFF('General',N,NRHS,B,LDB,X,LDX)
*
      Factorize A in the array AFB
*
      CALL DPBTRF(UPLO,N,KD,AFB,LDAFB,INFO)
*
      WRITE (NOUT,*)
      IF (INFO.EQ.0) THEN
*
*         Compute solution in the array X
*
        CALL DPBTRS(UPLO,N,KD,NRHS,AFB,LDAFB,X,LDX,INFO)
*
*         Improve solution, and compute backward errors and
*         estimated bounds on the forward errors
*
        CALL DPBRFS(UPLO,N,KD,NRHS,AB,LDAB,AFB,LDAFB,B,LDB,X,LDX,
+          FERR,BERR,WORK,IWORK,INFO)
*
*         Print solution
*
        IFAIL = 0
*
        CALL X04CAF('General',' ',N,NRHS,X,LDX,'Solution(s)',IFAIL)
*
        WRITE (NOUT,*)
        WRITE (NOUT,*) 'Backward errors (machine-dependent)'
        WRITE (NOUT,99999) (BERR(J),J=1,NRHS)
        WRITE (NOUT,*)
+        'Estimated forward error bounds (machine-dependent)'
        WRITE (NOUT,99999) (FERR(J),J=1,NRHS)
      ELSE
        WRITE (NOUT,*) 'A is not positive-definite'
      END IF
    END IF
*
99999 FORMAT ((3X,1P,7E11.1))
      END

```

## 9.2 Program Data

F07HHF Example Program Data

|       |        |       |      |  |                           |
|-------|--------|-------|------|--|---------------------------|
| 4     | 1      | 2     |      |  | :Values of N, KD and NRHS |
| 'L'   |        |       |      |  | :Value of UPLO            |
| 5.49  |        |       |      |  |                           |
| 2.68  | 5.63   |       |      |  |                           |
|       | -2.39  | 2.60  |      |  |                           |
|       |        | -2.22 | 5.17 |  | :End of matrix A          |
| 22.09 | 5.10   |       |      |  |                           |
| 9.31  | 30.81  |       |      |  |                           |
| -5.24 | -25.82 |       |      |  |                           |
| 11.83 | 22.90  |       |      |  | :End of matrix B          |

## 9.3 Program Results

F07HHF Example Program Results

Solution(s)

|   | 1       | 2       |
|---|---------|---------|
| 1 | 5.0000  | -2.0000 |
| 2 | -2.0000 | 6.0000  |
| 3 | -3.0000 | -1.0000 |
| 4 | 1.0000  | 4.0000  |

Backward errors (machine-dependent)

4.4E-17      9.2E-17

Estimated forward error bounds (machine-dependent)

2.0E-14      2.9E-14

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