

NAG Library Routine Document

F04JGF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of ***bold italicised*** terms and other implementation-dependent details.

1 Purpose

F04JGF finds the solution of a linear least-squares problem, $Ax = b$, where A is a real m by n ($m \geq n$) matrix and b is an m element vector. If the matrix of observations is not of full rank, then the minimal least-squares solution is returned.

2 Specification

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SUBROUTINE F04JGF(M, N, A, LDA, B, TOL, SVD, SIGMA, IRANK, WORK, LWORK,
1              IFAIL)
    INTEGER          M, N, LDA, IRANK, LWORK, IFAIL
    double precision A(LDA,N), B(M), TOL, SIGMA, WORK(LWORK)
    LOGICAL          SVD

```

3 Description

The minimal least-squares solution of the problem $Ax = b$ is the vector x of minimum (Euclidean) length which minimizes the length of the residual vector $r = b - Ax$.

The real m by n ($m \geq n$) matrix A is factorized as

$$A = Q \begin{pmatrix} U \\ 0 \end{pmatrix}$$

where Q is an m by m orthogonal matrix and U is an n by n upper triangular matrix. If U is of full rank, then the least-squares solution is given by

$$x = (U^{-1}0)Q^T b.$$

If U is not of full rank, then the singular value decomposition of U is obtained so that U is factorized as

$$U = RDP^T,$$

where R and P are n by n orthogonal matrices and D is the n by n diagonal matrix

$$D = \text{diag}(\sigma_1, \sigma_2, \dots, \sigma_n),$$

with $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_n \geq 0$, these being the singular values of A . If the singular values $\sigma_{k+1}, \dots, \sigma_n$ are negligible, but σ_k is not negligible, relative to the data errors in A , then the rank of A is taken to be k and the minimal least-squares solution is given by

$$x = P \begin{pmatrix} S^{-1} & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} R^T & 0 \\ 0 & I \end{pmatrix} Q^T b,$$

where $S = \text{diag}(\sigma_1, \sigma_2, \dots, \sigma_k)$.

This routine obtains the factorizations by a call to F02WDF.

The routine also returns the value of the standard error

$$\begin{aligned} \sigma &= \sqrt{\frac{r^T r}{m-k}}, & \text{if } m > k, \\ &= 0, & \text{if } m = k, \end{aligned}$$

$r^T r$ being the residual sum of squares and k the rank of A .

4 References

Lawson C L and Hanson R J (1974) *Solving Least-squares Problems* Prentice–Hall

5 Parameters

- 1: M – INTEGER *Input*
On entry: m , the number of rows of A .
Constraint: $M \geq N$.

- 2: N – INTEGER *Input*
On entry: n , the number of columns of A .
Constraint: $1 \leq N \leq M$.

- 3: A(LDA,N) – **double precision** array *Input/Output*
On entry: the m by n matrix A .
On exit: if SVD is returned as .FALSE., A is overwritten by details of the QU factorization of A (see F02WDF for further details).
 If SVD is returned as .TRUE., the first n rows of A are overwritten by the right-hand singular vectors, stored by rows; and the remaining rows of the array are used as workspace.

- 4: LDA – INTEGER *Input*
On entry: the first dimension of the array A as declared in the (sub)program from which F04JGF is called.
Constraint: $LDA \geq M$.

- 5: B(M) – **double precision** array *Input/Output*
On entry: the right-hand side vector b .
On exit: the first n elements of B contain the minimal least-squares solution vector x . The remaining $m - n$ elements are used for workspace.

- 6: TOL – **double precision** *Input*
On entry: a relative tolerance to be used to determine the rank of A . TOL should be chosen as approximately the largest relative error in the elements of A . For example, if the elements of A are correct to about 4 significant figures then TOL should be set to about 5×10^{-4} . See Section 8 for a description of how TOL is used to determine rank. If TOL is outside the range $(\epsilon, 1.0)$, where ϵ is the **machine precision**, then the value ϵ is used in place of TOL. For most problems this is unreasonably small.

- 7: SVD – LOGICAL *Output*
On exit: is returned as .FALSE. if the least-squares solution has been obtained from the QU factorization of A . In this case A is of full rank. SVD is returned as .TRUE. if the least-squares solution has been obtained from the singular value decomposition of A .

- 8: SIGMA – **double precision** *Output*
On exit: the standard error, i.e., the value $\sqrt{r^T r / (m - k)}$ when $m > k$, and the value zero when $m = k$. Here r is the residual vector $b - Ax$ and k is the rank of A .

9: IRANK – INTEGER

Output

On exit: k , the rank of the matrix A . It should be noted that it is possible for IRANK to be returned as n and SVD to be returned as .TRUE.. This means that the matrix U only just failed the test for nonsingularity.

10: WORK(LWORK) – *double precision* array

Output

On exit: if SVD is returned as .FALSE., then the first n elements of WORK contain information on the QU factorization of A (see parameter A above and F02WDF), and $WORK(n+1)$ contains the condition number $\|U\|_E \|U^{-1}\|_E$ of the upper triangular matrix U .

If SVD is returned as .TRUE., then the first n elements of WORK contain the singular values of A arranged in descending order and $WORK(n+1)$ contains the total number of iterations taken by the QR algorithm. The rest of WORK is used as workspace.

11: LWORK – INTEGER

Input

On entry: the dimension of the array WORK as declared in the (sub)program from which F04JGF is called.

Constraint: $LWORK \geq 4 \times N$.

12: IFAIL – INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this parameter you should refer to Section 3.3 in the Essential Introduction for details.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, if you are not familiar with this parameter, the recommended value is 0. **When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.**

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1 , explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

On entry, $N < 1$,
or $M < N$,
or $LDA < M$,
or $LWORK < 4 \times N$.

IFAIL = 2

The QR algorithm has failed to converge to the singular values in $50 \times N$ iterations. This failure can only happen when the singular value decomposition is employed, but even then it is not likely to occur.

7 Accuracy

The computed factors Q , U , R , D and P^T satisfy the relations

$$Q \begin{pmatrix} U \\ 0 \end{pmatrix} = A + E, Q \begin{pmatrix} R & 0 \\ 0 & I \end{pmatrix} \begin{pmatrix} D \\ 0 \end{pmatrix} P^T = A + F,$$

where

$$\|E\|_2 \leq c_1 \epsilon \|A\|_2,$$

$$\|F\|_2 \leq c_2 \epsilon \|A\|_2,$$

ϵ being the **machine precision**, and c_1 and c_2 being modest functions of m and n . Note that $\|A\|_2 = \sigma_1$. For a fuller discussion, covering the accuracy of the solution x see Lawson and Hanson (1974), especially pages 50 and 95.

8 Further Comments

If the least-squares solution is obtained from the QU factorization then the time taken by the routine is approximately proportional to $n^2(3m - n)$. If the least-squares solution is obtained from the singular value decomposition then the time taken is approximately proportional to $n^2(3m + 19n)$. The approximate proportionality factor is the same in each case.

This routine is column biased and so is suitable for use in paged environments.

Following the QU factorization of A the condition number

$$c(U) = \|U\|_E \|U^{-1}\|_E$$

is determined and if $c(U)$ is such that

$$c(U) \times \text{TOL} > 1.0$$

then U is regarded as singular and the singular values of A are computed. If this test is not satisfied, U is regarded as nonsingular and the rank of A is set to n . When the singular values are computed the rank of A , say k , is returned as the largest integer such that

$$\sigma_k > \text{TOL} \times \sigma_1,$$

unless $\sigma_1 = 0$ in which case k is returned as zero. That is, singular values which satisfy $\sigma_i \leq \text{TOL} \times \sigma_1$ are regarded as negligible because relative perturbations of order TOL can make such singular values zero.

9 Example

This example obtains a least-squares solution for $r = b - Ax$, where

$$A = \begin{pmatrix} 0.05 & 0.05 & 0.25 & -0.25 \\ 0.25 & 0.25 & 0.05 & -0.05 \\ 0.35 & 0.35 & 1.75 & -1.75 \\ 1.75 & 1.75 & 0.35 & -0.35 \\ 0.30 & -0.30 & 0.30 & 0.30 \\ 0.40 & -0.40 & 0.40 & 0.40 \end{pmatrix}, \quad b = \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \end{pmatrix}$$

and the value TOL is to be taken as 5×10^{-4} .

9.1 Program Text

```
*      F04JGF Example Program Text
*      Mark 14 Revised. NAG Copyright 1989.
*      .. Parameters ..
      INTEGER          MMAX, NMAX, LDA, LWORK
      PARAMETER        (MMAX=8, NMAX=MMAX, LDA=MMAX, LWORK=4*NMAX)
      INTEGER          NIN, NOUT
      PARAMETER        (NIN=5, NOUT=6)
*      .. Local Scalars ..
      DOUBLE PRECISION SIGMA, TOL
      INTEGER          I, IFAIL, IRANK, J, M, N
      LOGICAL          SVD
*      .. Local Arrays ..
      DOUBLE PRECISION A(LDA,NMAX), B(MMAX), WORK(LWORK)
*      .. External Subroutines ..
```

```

      EXTERNAL          F04JGF
*      .. Executable Statements ..
      WRITE (NOUT,*) 'F04JGF Example Program Results'
*      Skip heading in data file
      READ (NIN,*)
      READ (NIN,*) M, N
      TOL = 5.0D-4
      WRITE (NOUT,*)
      IF (M.GT.0 .AND. M.LE.MMAX .AND. N.GT.0 .AND. N.LE.NMAX) THEN
        READ (NIN,*) ((A(I,J),J=1,N),I=1,M)
        READ (NIN,*) (B(I),I=1,M)
        IFAIL = 1
*
        CALL F04JGF(M,N,A,LDA,B,TOL,SVD,SIGMA,IRANK,WORK,LWORK,IFAIL)
*
        IF (IFAIL.EQ.0) THEN
          WRITE (NOUT,*) 'Solution vector'
          WRITE (NOUT,99996) (B(I),I=1,N)
          WRITE (NOUT,*)
          WRITE (NOUT,99998) 'Standard error = ', SIGMA,
+            ' Rank = ', IRANK
          WRITE (NOUT,*)
          WRITE (NOUT,99997) 'SVD = ', SVD
        ELSE
          WRITE (NOUT,99995) IFAIL
        END IF
      ELSE
        WRITE (NOUT,99999) 'M or N out of range: M = ', M, ' N = ', N
      END IF
*
99999 FORMAT (1X,A,I5,A,I5)
99998 FORMAT (1X,A,F6.3,A,I2)
99997 FORMAT (1X,A,L2)
99996 FORMAT (1X,8F9.3)
99995 FORMAT (1X,' ** F04JGF returned with IFAIL = ',I5)
      END

```

9.2 Program Data

F04JGF Example Program Data

6	4				
0.05	0.05	0.25	-0.25		
0.25	0.25	0.05	-0.05		
0.35	0.35	1.75	-1.75		
1.75	1.75	0.35	-0.35		
0.30	-0.30	0.30	0.30		
0.40	-0.40	0.40	0.40		
1.0	2.0	3.0	4.0	5.0	6.0

9.3 Program Results

F04JGF Example Program Results

Solution vector

4.967	-2.833	4.567	3.233
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Standard error = 0.909 Rank = 3

SVD = T