

NAG Library Routine Document

F02FHF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of ***bold italicised*** terms and other implementation-dependent details.

1 Purpose

F02FHF finds the eigenvalues of the generalized band symmetric eigenvalue problem $Ax = \lambda Bx$, where A and B are symmetric band matrices and B is positive-definite.

2 Specification

```
SUBROUTINE F02FHF(N, MA, A, LDA, MB, B, LDB, D, WORK, LWORK, IFAIL)
INTEGER          N, MA, LDA, MB, LDB, LWORK, IFAIL
double precision A(LDA,N), B(LDB,N), D(N), WORK(LWORK)
```

3 Description

The generalized band symmetric eigenvalue problem $Ax = \lambda Bx$, where A is a symmetric band matrix of band width $2m_A + 1$ and B is a positive-definite symmetric band matrix of band width $2m_B + 1$, is solved by a variant of the method of Crawford (see Crawford (1973)).

F02FHF first transforms the problem $Ax = \lambda Bx$ to a standard band symmetric eigenvalue problem $Cy = \lambda y$, where C is a band symmetric matrix of band width $2m_A + 1$, using F01BUF and F01BVF. This step involves the implicit inversion of the matrix B and so this routine should be used with caution if B is ill-conditioned with respect to inversion.

The eigenvalues of the standard problem $Cy = \lambda y$ are then obtained by reducing C to tridiagonal form and then applying the QL variant of the QR algorithm to the tridiagonal form, using F08HEF (DSBTRD) and F08JFF (DSTERF). The above-mentioned routines should be consulted for further information on the methods used.

Once the eigenvalues have been found by this routine, selected eigenvectors may be obtained by repeated calls to F02SDF with the original matrices A and B as data.

The routine assumes that $m_A \geq m_B$ and hence if the band width of A is actually smaller than that of B , then A must be filled out with additional zero diagonals.

4 References

Crawford C R (1973) Reduction of a band-symmetric generalized eigenvalue problem *Comm. ACM* **16** 41–44

Wilkinson J H (1977) Some recent advances in numerical linear algebra *The State of the Art in Numerical Analysis* (ed D A H Jacobs) Academic Press

5 Parameters

1: N – INTEGER *Input*
On entry: n , the order of the matrices A and B .
Constraint: $N \geq 1$.

- 2: MA – INTEGER *Input*
On entry: m_A , the number of superdiagonals within the band of A . Normally $m_A \ll n$.
Constraint: $0 \leq MA \leq N - 1$.
- 3: A(LDA,N) – **double precision** array *Input/Output*
On entry: the upper triangle of the n by n symmetric band matrix A , with the diagonal of the matrix stored in the $(m_A + 1)$ th row of the array, and the m_A superdiagonals within the band stored in the first m_A rows of the array. Each column of the matrix is stored in the corresponding column of the array. For example, if $n = 6$ and $m = 2$, the storage space is
- | | | | | | |
|----------|----------|----------|----------|----------|----------|
| * | * | a_{13} | a_{24} | a_{35} | a_{46} |
| * | a_{12} | a_{23} | a_{34} | a_{45} | a_{56} |
| a_{11} | a_{22} | a_{33} | a_{44} | a_{55} | a_{66} |
- Elements in the top left corner of the array need not be set. The following code assigns the matrix elements within the band to the correct elements of the array:
- ```

 MA1 = MA + 1
 DO 20 J = 1, N
 DO 10 I = MAX(1,J-MA1+1), J
 A(I-J+MA1,J) = matrix (I,J)
 10 CONTINUE
 20 CONTINUE

```
- On exit:*  $A$  is overwritten by the corresponding elements of  $C$ .
- 4: LDA – INTEGER *Input*  
*On entry:* the first dimension of the array  $A$  as declared in the (sub)program from which F02FHF is called.  
*Constraint:*  $LDA \geq MA + 1$ .
- 5: MB – INTEGER *Input*  
*On entry:*  $m_B$ , the number of superdiagonals within the band of  $B$ .  
*Constraint:*  $0 \leq MB \leq MA$ .
- 6: B(LDB,N) – **double precision** array *Input/Output*  
*On entry:* the upper triangle of the  $n$  by  $n$  symmetric positive-definite band matrix  $B$ , with the diagonal of the matrix stored in the  $(m_B + 1)$ th row of the array, and the  $m_B$  superdiagonals within the band stored in the first  $m_B$  rows of the array. Each column of the matrix is stored in the corresponding column of the array.  
*On exit:*  $B$  is overwritten.
- 7: LDB – INTEGER *Input*  
*On entry:* the first dimension of the array  $B$  as declared in the (sub)program from which F02FHF is called.  
*Constraint:*  $LDB \geq MB + 1$ .
- 8: D(N) – **double precision** array *Output*  
*On exit:* the eigenvalues in descending order of magnitude.
- 9: WORK(LWORK) – **double precision** array *Workspace*  
10: LWORK – INTEGER *Input*  
*On entry:* the dimension of the array  $WORK$  as declared in the (sub)program from which F02FHF is called.  
*Constraint:*  $LWORK \geq \max(N, (3 \times MA + MB) \times (MA + MB + 1))$ .

## 11: IFAIL – INTEGER

Input/Output

*On entry:* IFAIL must be set to 0,  $-1$  or  $1$ . If you are unfamiliar with this parameter you should refer to Section 3.3 in the Essential Introduction for details.

*On exit:* IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value  $-1$  or  $1$  is recommended. If the output of error messages is undesirable, then the value  $1$  is recommended. Otherwise, if you are not familiar with this parameter, the recommended value is  $0$ . **When the value  $-1$  or  $1$  is used it is essential to test the value of IFAIL on exit.**

## 6 Error Indicators and Warnings

If on entry IFAIL = 0 or  $-1$ , explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

On entry,  $N < 1$ ,  
 or  $MA < 0$ ,  
 or  $MA \geq N$ ,  
 or  $MB < 0$ ,  
 or  $MB > MA$ ,  
 or  $LDA \leq MA$ ,  
 or  $LDB \leq MB$ ,  
 or  $LWORK < \max(N, (3 \times MA + MB) \times (MA + MB + 1))$ .

IFAIL = 2

The matrix  $B$  is either not positive-definite or is nearly singular.

IFAIL = 3

This failure is very unlikely to occur, but indicates that more than  $30 \times N$  iterations are required by the  $QR$  part of the algorithm. The input parameters should be carefully checked to ensure that the error is not due to an incorrect parameter.

## 7 Accuracy

The computed eigenvalues will be the exact eigenvalues of a neighbouring problem  $(A + E)x = \lambda(B + F)x$ , where  $\|E\|$  and  $\|F\|$  are of the order of  $\epsilon c(B)\|A\|$  and  $\epsilon c(B)\|B\|$  respectively, where  $c(B)$  is the condition number of  $B$  with respect to inversion and  $\epsilon$  is the **machine precision**.

Thus if  $B$  is ill-conditioned with respect to inversion there may be a severe loss of accuracy in well-conditioned eigenvalues.

## 8 Further Comments

The time taken by F02FHF is very approximately proportional to  $n^2 \left( \frac{m_A + m_B + 2}{m_A} + \frac{m_B^2}{8} \right)$ , provided  $m_A > 0$ .

## 9 Example

This example finds the eigenvalues of the generalized band symmetric eigenvalue problem  $Ax = \lambda Bx$ , where

$$A = \begin{pmatrix} 5 & 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 6 & 2 & -1 & 0 & 0 & 0 & 0 & 0 \\ -1 & 2 & 7 & 3 & -1 & 0 & 0 & 0 & 0 \\ 0 & -1 & 3 & 8 & 4 & -1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 4 & 9 & 4 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 4 & 8 & 3 & -1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 3 & 7 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 & -1 & 2 & 6 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 1 & 5 \end{pmatrix}$$

and

$$B = \begin{pmatrix} 4 & 2 & -2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 2 & 5 & 1 & -2 & 0 & 0 & 0 & 0 & 0 \\ -2 & 1 & 6 & 1 & -2 & 0 & 0 & 0 & 0 \\ 0 & -2 & 1 & 6 & 1 & -2 & 0 & 0 & 0 \\ 0 & 0 & -2 & 1 & 6 & 1 & -2 & 0 & 0 \\ 0 & 0 & 0 & -2 & 1 & 6 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 & -2 & 1 & 6 & 1 & -2 \\ 0 & 0 & 0 & 0 & 0 & -2 & 1 & 6 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & -2 & 1 & 6 \end{pmatrix}.$$

## 9.1 Program Text

```

* F02FHF Example Program Text
* Mark 14 Revised. NAG Copyright 1989.
* .. Parameters ..
 INTEGER NMAX, MAMAX, MBMAX, LDA, LDB, LWORK
 PARAMETER (NMAX=20,MAMAX=5,MBMAX=5,LDA=MAMAX+1,LDB=MBMAX+1,
+ LWORK=NMAX+(3*MAMAX+MBMAX)*(MAMAX+MBMAX+2))
 INTEGER NIN, NOUT
 PARAMETER (NIN=5,NOUT=6)
* .. Local Scalars ..
 INTEGER I, IFAIL, J, MA, MB, N
* .. Local Arrays ..
 DOUBLE PRECISION A(LDA,NMAX), B(LDB,NMAX), D(NMAX), WORK(LWORK)
* .. External Subroutines ..
 EXTERNAL F02FHF
* .. Executable Statements ..
 WRITE (NOUT,*) 'F02FHF Example Program Results'
* Skip heading in data file
 READ (NIN,*)
 READ (NIN,*) N, MA, MB
 WRITE (NOUT,*)
 IF (N.LT.1 .OR. N.GT.NMAX .OR. MA.LT.0 .OR. MA.GT.MAMAX .OR.
+ MB.LT.0 .OR. MB.GT.MBMAX) THEN
 WRITE (NOUT,*) 'N or MA or MB is out of range.'
 WRITE (NOUT,99999) 'N = ', N, ' MA = ', MA, ' MB = ', MB
 ELSE
 DO 20 I = 1, MA + 1
 READ (NIN,*) (A(I,J),J=1,N)
20 CONTINUE
 DO 40 I = 1, MB + 1
 READ (NIN,*) (B(I,J),J=1,N)
40 CONTINUE
*
 IFAIL = 1
*
 CALL F02FHF(N,MA,A,LDA,MB,B,LDB,D,WORK,LWORK,IFAIL)
*
 IF (IFAIL.EQ.0) THEN
 WRITE (NOUT,*) 'Eigenvalues'
 WRITE (NOUT,99998) (D(J),J=1,N)
 ELSE
 WRITE (NOUT,99997) IFAIL

```

```

 END IF
 END IF
*
99999 FORMAT (1X,A,I5,A,I5,A,I5)
99998 FORMAT (1X,7F9.4)
99997 FORMAT (1X,' ** F02FHF returned with IFAIL = ',I5)
 END

```

## 9.2 Program Data

F02FHF Example Program Data

|     |     |      |      |      |      |      |      |      |  |
|-----|-----|------|------|------|------|------|------|------|--|
| 9   | 2   | 2    |      |      |      |      |      |      |  |
| 0.0 | 0.0 | -1.0 | -1.0 | -1.0 | -1.0 | -1.0 | -1.0 | -1.0 |  |
| 0.0 | 1.0 | 2.0  | 3.0  | 4.0  | 4.0  | 3.0  | 2.0  | 1.0  |  |
| 5.0 | 6.0 | 7.0  | 8.0  | 9.0  | 8.0  | 7.0  | 6.0  | 5.0  |  |
| 0.0 | 0.0 | -2.0 | -2.0 | -2.0 | -2.0 | -2.0 | -2.0 | -2.0 |  |
| 0.0 | 2.0 | 1.0  | 1.0  | 1.0  | 1.0  | 1.0  | 1.0  | 1.0  |  |
| 4.0 | 5.0 | 6.0  | 6.0  | 6.0  | 6.0  | 6.0  | 6.0  | 6.0  |  |

## 9.3 Program Results

F02FHF Example Program Results

Eigenvalues

|        |        |        |        |        |        |        |
|--------|--------|--------|--------|--------|--------|--------|
| 0.0544 | 0.7578 | 0.8277 | 0.9188 | 0.9429 | 1.1667 | 1.5582 |
| 2.6623 | 4.7791 |        |        |        |        |        |

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